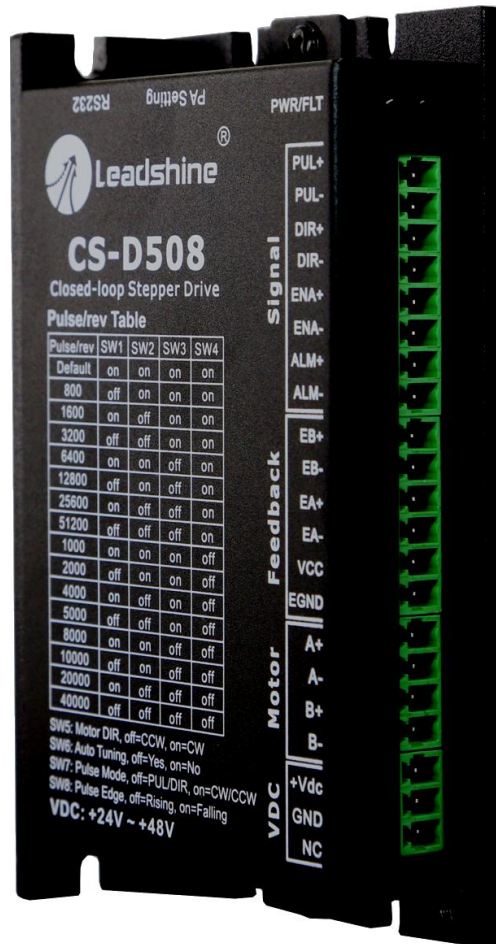


User Manual

CS-D508

Closed Loop Stepper Drive



Revision 1.0

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Notice

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Record of Revisions

| Revision | Date | Description of Release |
|----------|-----------------|------------------------|
| 1.0 | September, 2017 | Initial Release |

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1. Introduction

Leadshine CS-D508 is a closed loop stepper drive designed to solve the loss of step problem in open loop stepper control systems, thus increase system reliability at minimal cost increase. It implements advanced control algorithm of Leadshine based on its tens of years' experience in stepper and servo controls. The CS-D508 is highly reliable and affordable and performs excellent in many industrial applications such as CNC, medical, electronics, packaging...

The CS-D508 can power 2-phase NEMA 17, 23, and 24 stepper motors with incremental encoders. Compared with traditional open loop stepper systems, a CS-D508 adopted closed loop step system can eliminate potential loss of step, make real-time position error correction, and do not need torque reservation (100% torque implementation). Also it can power the driven stepper motor with reduced heating, lower noise, low vibration...

1.1 Features

- No loss of step
- No torque reservation
- No hunting or overshooting
- No tuning for easy setup
- Low noise and vibration, smooth motion
- 20-50VDC supply voltage, max 8A output current
- Max 200 KHz input frequency
- 15 micro step settings of 800-51,200 via DIP switches, or 200-51,200 via software (increase by 200)
- Protections for over voltage, over current and position following error

1.2 Applications

When a CS-D508 closed loop stepper drive is implemented with a compatible stepper motor with encoder, the closed stepper system can be adopted in many small to median speed applications such as CNC routers, CNC mills, CNC laser cutters, CNC plasmas, lab automation instruments, plotters, medical equipment, electronic equipment, small packaging machines, etc.

2. Specifications

2.1 Electrical Specifications

| Parameters | Min | Typical | Max | Unit |
|-------------------------|-----|------------|-----------|------|
| Output Current | 0.5 | - | 8.0(Peak) | A |
| Operating Voltage | 20 | 24, 36, 48 | 50 | VDC |
| Logic signal current | 7 | 10 | 16 | mA |
| Pulse input frequency | 0 | - | 200 | kHz |
| Minimal pulse width | 2.5 | - | - | μS |
| Minimal direction setup | 5.0 | - | - | μS |
| Isolation resistance | 500 | | | MΩ |

2.2 Environment

| Cooling | Natural Cooling or Forced Cooling | |
|-----------------------|-----------------------------------|---|
| Operating Environment | Environment | Avoid dust, oil fog and corrosive gases |
| | Ambient Temperature | 0 °C — 65 °C (32 °F - 149 °F) |
| | Humidity | 40%RH—90%RH |
| | Operating Temperature | 0 °C — 50 °C (32 °F - 122 °F) |
| | Vibration | 10-50Hz / 0.15mm |
| Storage Temperature | -20 °C — 65 °C (-4 °F - 149 °F) | |
| Weight | Approx. 280 g (9.9 Oz) | |

2.3 Mechanical Specifications

(unit: mm [1inch=25.4mm])

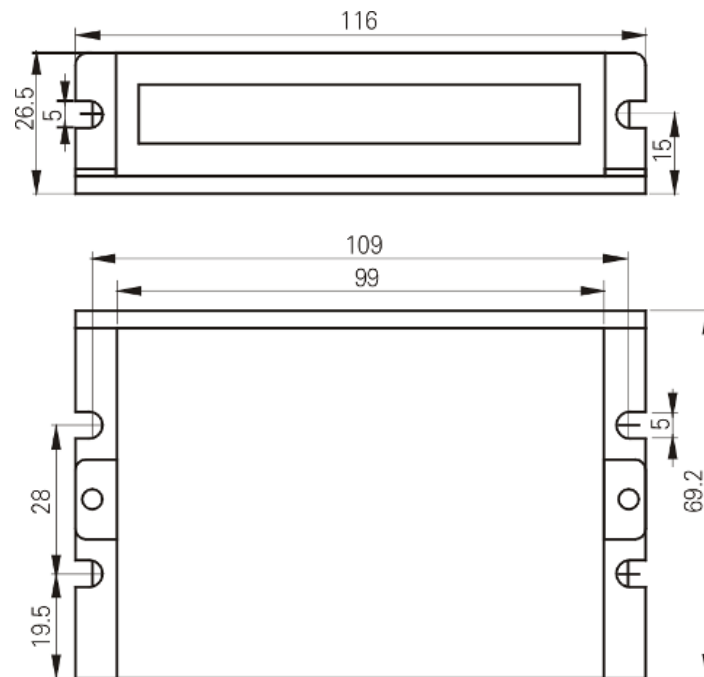


Figure 1: Mechanical specifications

2.4 Heat Dissipation

- CS-D508 reliable working temperature should be no more than 60°C (140 °F)
- It is recommended to mount the drive vertically to maximize heat dissipation. Mount a cooling fan nearby if necessary.
- If multiple CS-D508 drives are installed, it is suggested to keep a minimal 30mm (1.2 inches) between two of them.

3. Connections and LED Indication

A CS-D508 closed loop stepper drive has 5 connection blocks from P1 to P5 (see figure 2).

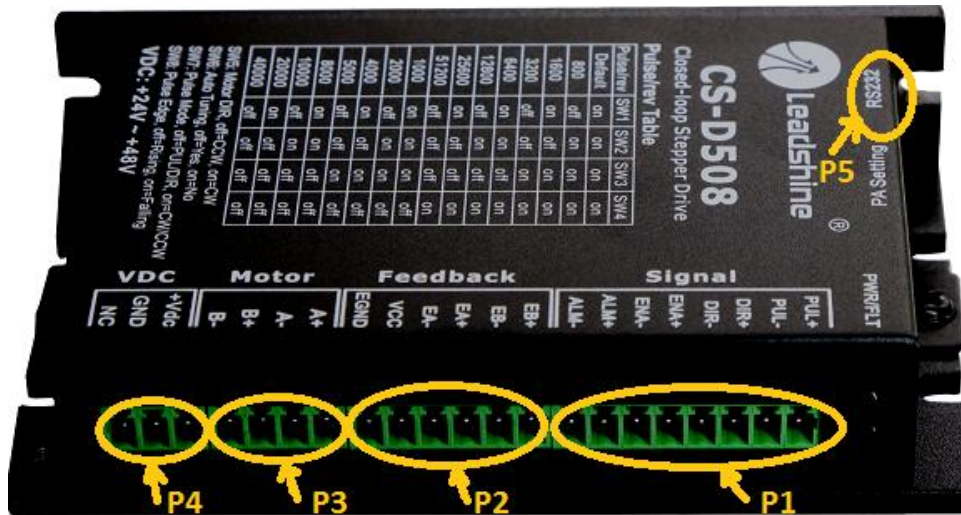


Figure 2: CS-D508 connectors

3.1 Connector P1 – Control and Fault Output Connections

3.1.1 Pin Assignments of P1

The P1 connector in Figure 2 is for control signal and fault output connections. Refer to the following table for details.

| Pin Name | I/O | Details |
|----------|-----|--|
| PUL+ | I | <u>Pulse signal:</u> (1). In single pulse (pulse & direction) control mode, this input represents pulse signal. A pulse signal is active at the rising or falling voltage edge (set by DIP switch SW8). (2). In double-pulse (CW/CCW) control mode (set by DIP switch SW7), this signal input represents clockwise (CW) pulse, and is active at both high voltage level and low voltage level. (3). 4.5-24V for voltage HIGH, 0-0.5V for voltage LOW (same for DIR and ENA signals). (4). Pulse width should be set to 2.5μs or longer. |
| PUL- | I | |
| DIR+ | I | <u>Direction signal:</u> (1). In single pulse (step & direction) control mode, this signal's low and high voltage levels represent the two directions of motor rotation (e.g. clockwise and counterclockwise). (2). In double-pulse (CW & CCW) control mode, this signal represents counterclockwise (CCW) rotation. It is active at both voltage high level and low level. (3). Minimal DIR signal setup time should be at least 5μs. (4). Rotation direction is related to your motor/drive wiring. You can reverse the default rotation direction by toggling the SW5 DIP switch. |
| DIR- | I | |
| ENA+ | I | <u>Enable signal:</u> This signal is used for enabling/disabling the drive. High voltage level of 4.5-24V (NPN control signal) for enabling the drive and low voltage level of 0-0.5VDC for disabling the drive. PNP and Differential control signals are on the contrary, namely Low level for enabling. By default this signal is left UNCONNECTED & ENABLED . |
| ENA- | I | |

| | | |
|-------------|----------|---|
| ALM+ | O | Fault Signal: An OC output signal which is active when one of the following error protection is activated: over-voltage, over-current, and position following error. This port can sink or source 20mA current at 24V. The resistance between ALM+ and ALM- is low impedance in normal operation, and will change to high when the drive goes into error protection. The voltage active level of this false output signal can be configured by configuration software. |
| ALM- | O | |

Notes: (1) Shielding control signal wires is suggested; (2) to avoid/reduce interference, don't tie control signal cables and power wires together.

3.1.2 Typical Control and Fault Output Connections

The CS-D508 can accept differential and single-ended control signal inputs (open-collector and PNP output). A CS-D508 has 3 optically isolated control inputs, PUL, DIR, and ENA. Refer to the following two figures for connections of open-collector and PNP signals.

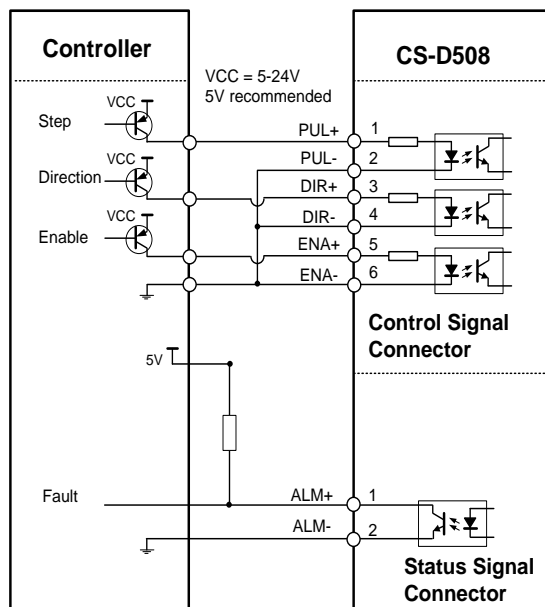


Figure 3: Connections to PNP signal
(Common-cathode)

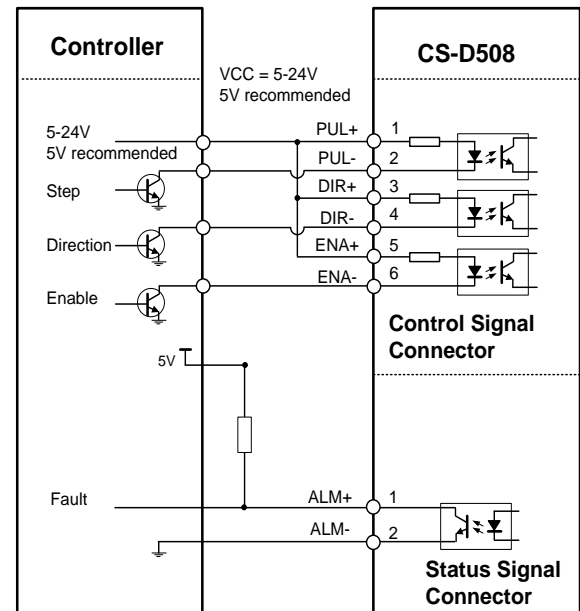


Figure 4: Connections to open-collector signal
(Common-anode)

3.2 Connector P2 - Encoder Connection

The P2 connector in Figure 2 is for encoder signal connection. Refer to the following table for details.

| Drive Pin Name | Description |
|----------------|---------------------------------------|
| EB+ | Encoder B+ input connection |
| EB- | Encoder B- input connection |
| EA+ | Encoder A+ input connection |
| EA- | Encoder A- input connection |
| VCC | encoder +5V voltage output connection |
| EGND | Power ground connection |

Notes: encoder resolution must be 1000-line.

3.3 Connector P3 - Motor Connection

The P3 connector in Figure 2 is for motor connection. Refer to the following table for details.

| Pin Name | Details |
|-----------|--|
| A+ | Stepper motor A+ connection. Connect motor A+ wire to this pin |
| A- | Stepper motor A- connection. Connect motor A- wire to this pin |
| B+ | Stepper motor B+ connection. Connect motor B+ wire to this pin |
| B- | Stepper motor B- connection. Connect motor B- wire to this pin |

3.4 Connector P4 – Power Supply Connection

The P4 connector in Figure 2 is for power supply connection. Refer to the following table for details.

| Pin Name | Details |
|-------------|---|
| +Vdc | Power supply positive connection. 20-50VDC power supply voltage |
| GND | Power supply ground connection. |

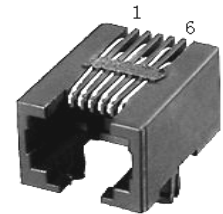
Notes: see Appendix B for compatible Leadshine power supplies

3.5 Connector P5 – RS232 Connection

The P5 connector in Figure 2 is a RS232 communication port for PC connection. Refer to the following pin definitions.

RS232 Communication Port – RJ11

| Pin | Name | I/O | Description |
|----------|------------|-----|-------------------|
| 1 | NC | - | Not connected. |
| 2 | +5V | O | +5V power output. |
| 3 | TxD | O | RS232 transmit. |
| 4 | GND | GND | Ground. |
| 5 | RxD | I | RS232 receive. |
| 6 | NC | - | Not connected. |



Notes: RS232 connection of CS-D508 is for tuning purpose only, not for RS232 command controls.

3.6 LED Light Indication

There are two LED lights for CS-D508, one red and one green. The GREEN one is the power indicator which will be always on generally. The RED one is a protection indicator. It is off always when a CS-D508 operates normally, but will flash 1, 2 or 7 times in a 5-second period when error protection is enabled. Different number of flashes indicates different protection type (read Section 9).

4. Motor Selection

The CS-D508 is designed to power 2-phase (or 4-phase 0.9 degree) NEMA 17/23/24 stepper motors with 1000-line incremental encoders. Leadshine offers many high performance stepper motors compatible with the CS-D508 which you can find in the Appendix A of this document. The CS-D508 can also power similar stepper motors with 1000-line incremental encoders from third-party suppliers.

5. Power Supply Selection

The CS-D508 can power small and medium size closed loop stepper motors (frame size from NEMA17 to 24) from Leadshine (see Appendix A) or other motor manufacturers. To get good system performance, it is important to select proper supply voltage and output current. Generally speaking, supply voltage determines the high speed performance of the motor, while output current determines the output torque of the driven motor (particularly at lower speed). Higher supply voltage will allow higher motor speed to be achieved, at the price of more noise and heating. If the motion speed requirement is low, it's better to use lower supply voltage to decrease noise, heating and improve reliability.

Notes: See Appendix B at the end of this document for Leadshine CS-D508 compatible switching power supplies specially designed for stepper & servo controls.

5.1 Regulated or Unregulated Power Supply

Both regulated and unregulated power supplies can be used to supply the drive. However, unregulated power supplies are preferred due to their ability to withstand current surge and fast response for current change. If you prefer to a regulated power supply, it is suggested to choose such a power supply specially designed for stepper/servo controls such as Leadshine RPS series (<http://www.leadshine.com/producttypes.aspx?producttype=regulated-switching>). Or, in the case when only normal switching power supplies are available, it is important to use “OVERSIZE” high current output rating power supplies (for example, using a 4A power supply for 3A stepper motor) to avoid problems such as current clamp. On the other hand, if unregulated supply is used, one may use a power supply of lower current rating than that of motor (typically 50%-70% of motor current). The reason is that the drive draws current from the power supply capacitor of the unregulated supply only during the ON duration of the PWM cycle, but not during the OFF duration. Therefore, the average current withdrawn from power supply is considerably less than motor current. For example, two 3A motors can be well supplied by one power supply of 4A rating.

5.2 Power Supply Sharing

Multiple CS-D508 drives can share one power supply to save space and reduce cost, if that power supply has enough power capacity. To avoid cross interference, connect each stepper drive directly to the shared power supply separately. To avoid cross interference, DO NOT daisy-chain connect the power supply input pins of the Drivers. Instead connect them to power supply separately.

5.3 Selecting Supply Voltage

The CS-D508 is designed to operate within 20-50VDC voltage input. When selecting a power supply, besides voltage from the power supply power line voltage fluctuation and back EMF voltage generated during motor deceleration needs also to be taken into account. Ideally it is suggested to use a power supply with the output of 20-48VDC, leaving room for power line voltage fluctuation and back-EMF.

Higher supply voltage can increase motor torque at higher speeds, thus helpful for avoiding losing steps. However, higher voltage may cause bigger motor vibration at lower speed, and it may also cause over-voltage protection or even drive damage. Therefore, it is suggested to choose only sufficiently high supply voltage for intended applications.

6. DIP Switch Configurations

The CS-D508 has a built-in 8-bit DIP switch to set microstep resolution, motor direction, auto tuning switch and so on.

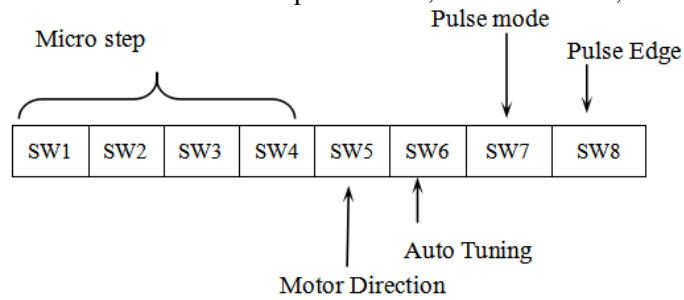


Figure 5 DIP switch Setting

6.1 Microstep Resolution (SW1-SW4)

Microstep resolution is set by SW1, 2, 3, 4 of the DIP switches as shown in the following table:

| Steps/Revolution | SW1 | SW2 | SW3 | SW4 |
|---|-----|-----|-----|-----|
| Software Configured (Defaulted to 1600) | on | on | on | on |
| 800 | off | on | on | on |
| 1600 | on | off | on | on |
| 3200 | off | off | on | on |
| 6400 | on | on | off | on |
| 12800 | off | on | off | on |
| 25600 | on | off | off | on |
| 51200 | off | off | off | on |
| 1000 | on | on | on | off |
| 2000 | off | on | on | off |
| 4000 | on | off | on | off |
| 5000 | off | off | on | off |
| 8000 | on | on | off | off |
| 10000 | off | on | off | off |
| 20000 | on | off | off | off |
| 40000 | off | off | off | off |

6.2 Other DIP Switch Settings (SW5-SW8)

| | Function | On | Off |
|-----|-------------------|-----------------------|------------------------|
| SW5 | Default Direction | CW (clockwise) | CCW (counterclockwise) |
| SW6 | Auto Tuning | No | Yes |
| SW7 | Pulse Model | CW/CCW (double pulse) | PUL/DIR (single pulse) |
| SW8 | Pulse Edge | Falling | Rising |

7. Typical Connection

A complete closed loop stepper system should include a stepper motor with encoder, CS-D508 drive, power supply and controller (pulse generator). A typical connection is illustrated in figure 6.

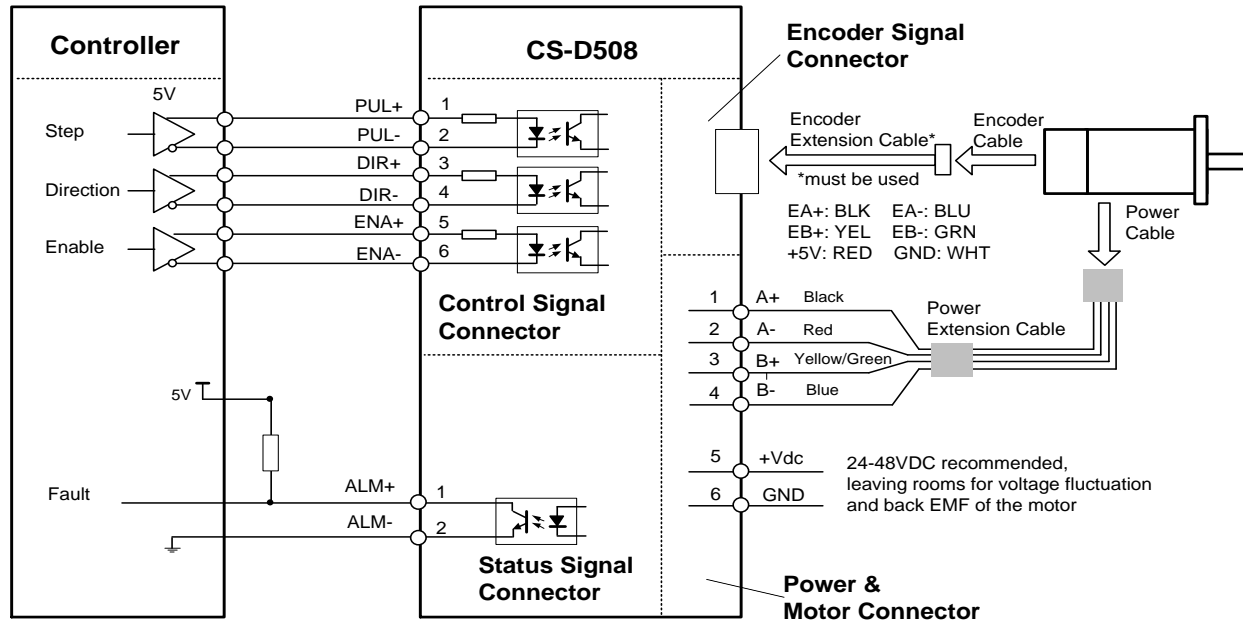


Figure 6: Typical connection

8. Sequence Chart of Control Signals

In order to avoid some fault operations and deviations, PUL, DIR and ENA should abide by some rules, shown as following diagram:

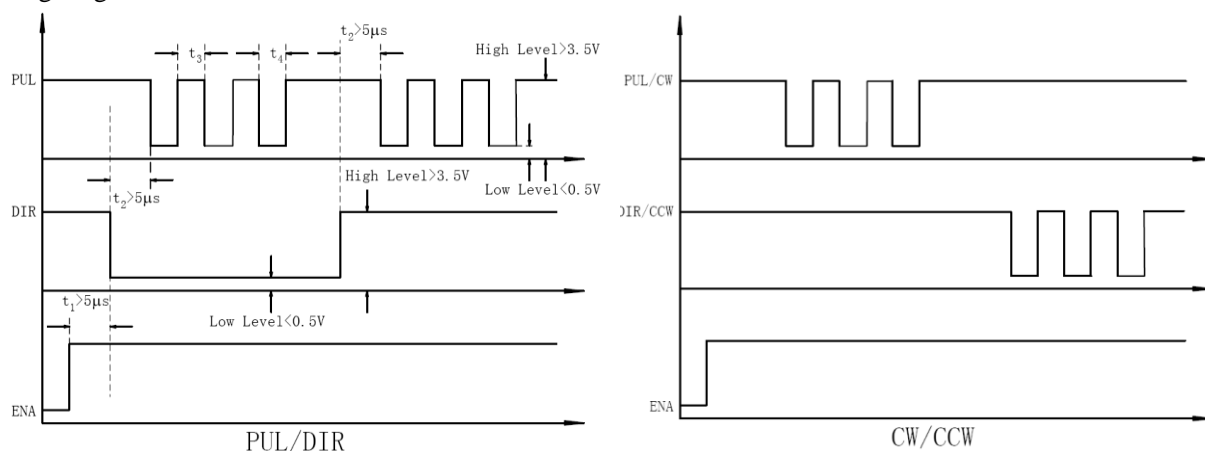


Figure 7: Sequence chart of control signals

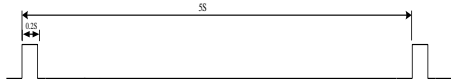
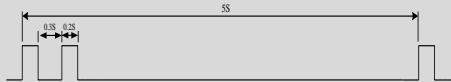
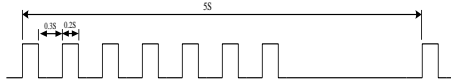
Remark:

- t_1 : ENA must be ahead of DIR by at least $5\mu s$. Usually, ENA+ and ENA- are NC (not connected). See "Connector P1 Configurations" for more information.
- t_2 : DIR must be ahead of PUL effective edge by $5\mu s$ to ensure correct direction;
- t_3 : Pulse width not less than $2.5\mu s$;

- d) t4: Low level width not less than 2.5 μ s.

9. Protection Functions

To improve reliability, the drive incorporates some built-in protections features.

| Priority | Time(s) of Blink | Sequence wave of red LED | Description |
|----------|------------------|---|--|
| 1st | 1 |  | Over-current protection activated when peak current exceeds the limit. |
| 2nd | 2 |  | Over-voltage protection activated when drive working voltage is greater than 90VDC |
| 3rd | 7 |  | Position following error |

When above protections are active, the motor shaft will be free or the red LED blinks. Reset the drive by repowering it to make it function properly after removing above problems.

10. Software Configuration

The CS-D508 is designed for simple setup and implementation. For most applications no software configuration or tuning is needed especially when driving Leadshine stepper motors with encoders (see Appendix A). If you want to do fine tuning or custom configurations such as micro-step, current percentage change..., you can use Leadshine's free ProTuner software to make the changes. Download ProTuner at

http://www.leadshine.com/UploadFile/Down/ProTuner_CS_Ds.V1.0.zip or

http://www.leadshineusa.com/UploadFile/Down/ProTuner_CS_Ds.V1.0.zip. Download the software manual at

http://www.leadshine.com/UploadFile/Down/CS-Dsm_V1.0.pdf or

http://www.leadshineusa.com/UploadFile/Down/CS-Dsm_V1.0.pdf.

11. Accessories

If you plan to use the ProTuner software, contact your supplier or Leadshine to purchase the RS232 cable with part number [1.4.4-0609505-B3](#) for connecting the CS-D508 to a computer with Windows XP / 7 installed. In the case of using USB to RS232 conversion, contact your supplier or Leadshine for such a cable with part number [USBTtoRS232](#) which has been verified working fine.



[1.4.4-0609505-B3](#)
(RS232 tuning cable)



[USBTtoRS232](#)
(USB to RS232 Conversion Cable)

12. Troubleshooting

In the event that your drive doesn't operate properly, the first step is to identify whether the problem is electrical or mechanical in nature. The next step is to isolate the system component that is causing the problem. As part of this process you may have to disconnect the individual components that make up your system and verify that they operate independently. It is important to document each step in the troubleshooting process. You may need this documentation to refer back to at a later date, and these details will greatly assist our Technical Support staff in determining the problem should you need assistance.

Many of the problems that affect motion control systems can be traced to electrical noise, controller software errors, or mistake in wiring.

| Symptoms | Possible Problems | Solutions |
|--|--|--|
| Motor is not rotating | No power | Connect power supply correctly |
| | Microstep resolution setting is wrong | Setting appropriate microstep |
| | Fault condition exists | Check wiring and restart power |
| | The drive is disabled | Drive restore factory setting, and keep ENA+, ENA- input signals unconnected. |
| Wrong motor rotation direction | The Direction signal level is reverse | Toggling the SW5 DIP switch |
| The drive in fault | Red light flashes once in a 5-second period | The motor coil may short circuit or exiting the wrong wiring |
| | Red light flashes twice in a 5-second period | The power supply exceeds Max. operation voltage |
| | Red light is always on after power on | The drive is burned |
| Erratic motor motion | Control signal is too weak | Ensure the current of control signal is within 7-16mA |
| | Control signal is interfered | Don't tie the control signal cable with power cable together |
| | Wrong motor connection | Refer to user manual of drive and motor datasheet |
| | Something wrong with motor coil | Check the motor is normal |
| Motor stalls during acceleration | Current setting is too small | Choose another power supply with lager power or increase the output current of drive |
| | Motor is undersized for the application | Choose another motor with higher torque |
| | Acceleration is set too high | Reduce the acceleration |
| | Power supply voltage too low | Choose another power supply with large voltage output |
| Excessive motor & drive heating | Inadequate heat sinking / cooling | Refer to chapter 2.4 |
| | Motor peak current setting is too high | Reduce the current value refer to motor datasheet |
| Motor vibration when power on | Speed loop Kp is too high | Reduce the speed loop Kp value |

13. Warranty

Twelve Month Warranty

Leadshine Technology Co., Ltd. warrants its products against defects in materials and workmanship for a period of 12 months from shipment out of factory. During the warranty period, Leadshine will either, at its option, repair or replace products which proved to be defective.

Exclusions

The above warranty does not extend to any product damaged by reasons of improper or inadequate handlings by customer, improper or inadequate customer wirings, unauthorized modification or misuse, or operation beyond the electrical specifications of the product and/or operation beyond environmental specifications for the product.

Obtaining Warranty Service

To obtain warranty service, please contact your seller to obtain a returned material authorization number (RMA) before returning product for service.

Shipping Failed Products

If your product fail during the warranty period, please contact your seller for how and where to ship the failed product for warranty or repair services first, you can also e-mail customer service at tech@leadshine.com to obtain a returned material authorization number (RMA) before returning product for service. Please include a written description of the problem along with contact name and address.

Appendix A. Leadshine CS-D508 Compatible Stepper Motors

The following Leadshine stepper motors with 1000-line encoders have been tested working with the CS-D508 closed loop stepper drive.

| Model | Frame Size (NEMA) | Torque (N.m / Oz-In) | Series | Length (mm / inch) | Notes |
|---------------|-------------------|----------------------|--------|--------------------|-----------------------------|
| CS-M21702 | 17 | 0.2 / 28 | CS-M | 56/2.20 | 0.197-inch (5-mm) shaft |
| CS-M21704 | | 0.4 / 57 | | 63/2.48 | 0.197-inch (5-mm) shaft |
| CS-M21706 | | 0.6 / 85 | | 70/2.76 | 0.197-inch (5-mm) shaft |
| CS-M21708 | | 0.8 / 113 | | 83/3.27 | 0.197-inch (5-mm) shaft |
| CS-M22306 | 23 | 0.6 / 85 | | 62/2.44 | 0.315-inch (8-mm) shaft |
| CS-M22313 | | 1.3 / 184 | | 77/3.03 | 0.315-inch (8-mm) shaft |
| CS-M22323 | | 2.3 / 326 | | 97/3.82 | 0.315-inch (8-mm) shaft |
| CS-M22323-S | | 2.3 / 326 | | 97/3.82 | 0.25-inch (6.35-mm) shaft |
| CS-M22326 | | 2.6 / 368 | | 105/4.13 | 0.315-inch (8-mm) shaft |
| CS-M22326-S | | 2.6 / 368 | | 105/4.13 | 0.25-inch (6.35-mm) shaft |
| CS-M22321-L | | 2.1 / 368 | | 88/3.46 | 0.315-inch (8-mm) shaft |
| CS-M22331-L | | 3.1 / 439 | | 109/4.29 | 0.315-inch (8-mm) shaft |
| CS-M22331-L-S | | 3.1 / 439 | | 109/4.29 | 0.375-inch (9.525-mm) shaft |
| ES-M22310 | 23 | 1.0 / 142 | ES-M | 73/2.87 | 0.315-inch (8-mm) shaft |
| ES-M22310-S | | 1.0/142 | | 73/2.87 | 0.25-inch (6.35-mm) shaft |
| ES-M22320 | | 2.0 / 283 | | 93/3.66 | 0.315-inch (8-mm) shaft |
| ES-M22320-S | | 2.0 / 283 | | 93/3.66 | 0.25-inch (6.35-mm) shaft |
| ES-M22320B | | 2.0 / 283 | | 131/5.16 | with 24VDC brake |
| ES-M22430 | 24 | 3.0 / 425 | | 103/4.06 | 0.315-inch (8-mm) shaft |

Note: all above stepper motors are mounted with 1000-line incremental encoders

Appendix B. Leadshine CS-D508 Compatible Power Supplies

It is highly suggested to use the following Leadshine power supplies to power CS-D508 to get optimized performance. Those power supply are specially designed for stepper and servo controls.

| Model | Output Voltage (VDC) | Series Model | Continuous Current (A) | Max Current (A) | Input Voltage (VAC) |
|------------|----------------------|--------------|------------------------|-----------------|---------------------|
| RPS2410V20 | 24 | RPS | 10 | 30 | 85-132 / 176-264 |
| RPS3611V20 | 36 | | 11 | 33 | 85-132 / 176-264 |
| RPS488V20 | 48 | | 8.3 | 24.9 | 85-132 / 176-264 |
| RPS4810V20 | 48 | | 10.5 | 31.5 | 85-132 / 176-264 |
| RPS2410 | 24 | | 10 | 12 | 85-132 / 176-264 |
| RPS369 | 36 | | 9.7 | 11 | 85-132 / 176-264 |
| RPS488 | 48 | | 7.3 | 8.5 | 85-132 / 176-264 |
| RPS4810 | 48 | | 10.4 | 12.5 | 85-132 / 176-264 |
| SPS407 | 42 | SPS | 7.0 | 9.0 | 180-240 |
| SPS407-L | 42 | | 4.7 | 9.0 | 90-130 |
| SPS487 | 48 | | 7.0 | 9.0 | 180-240 |
| SPS487-L | 48 | | 3.0 | 9.0 | 90-130 |